

B.Sc. Forensic Science: Semester-I	
FST105: Physics-I	
Teaching Scheme	Examination Scheme
Lectures: 3 hrs/Week	Class Test -12 Marks
Tutorials: 1 hr/Week	Teachers Assessment – 6 Marks
Credits: 4	Attendance – 12 Marks
	End Semester Exam – 70 marks

Course outcomes:

1. Recognize the difference between scalars, vectors, pseudo-scalars and pseudo-vectors.
2. Understand the physical interpretation of gradient, divergence and curl.
3. Comprehend the difference and connection between Cartesian, spherical and cylindrical coordinate systems.
4. Know the meaning of 4-vectors, Kronecker delta and Epsilon (Levi Civita) tensors.
5. Study the origin of pseudo forces in rotating frame.
6. Study the response of the classical systems to external forces and their elastic deformation.
7. Understand the dynamics of planetary motion and the working of Global Positioning System (GPS).
8. Comprehend the different features of Simple Harmonic Motion (SHM) and wave propagation.

Unit I – Coordinate Systems

- 2D & 3D Cartesian, Spherical and Cylindrical coordinate systems, basis vectors, transformation equations. Expressions for displacement vector, arc length, area element, volume element, gradient, divergence and curl in different coordinate systems. Components of velocity and acceleration in different coordinate systems. Examples of non-inertial coordinate system and pseudo-acceleration.

Unit II – Introduction to Tensors

- Principle of invariance of physical laws w.r.t. different coordinate systems as the basis for defining tensors. Coordinate transformations for general spaces of nD, contravariant, covariant & mixed tensors and their ranks, 4-vectors. Index notation and summation convention. Symmetric and skewsymmetric tensors. Invariant tensors, Kronecker delta and Epsilon (Levi Civita) tensors. Examples of tensors in physics.

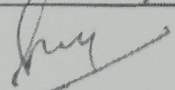
Unit III – Dynamics of a System of Particles

- Review of historical development of mechanics up to Newton. Background, statement and critical analysis of Newton's axioms of motion. Dynamics of a system of particles, centre of mass motion, and conservation laws & their deductions. Rotating frames of reference, general derivation of origin of pseudo forces (Euler, Coriolis & centrifugal) in rotating frame, and effects of Coriolis force.

Unit IV – Dynamics of a Rigid Body

- Angular momentum, Torque, Rotational energy and the inertia tensor. Rotational inertia for simple bodies (ring, disk, rod, solid and hollow sphere, solid and hollow cylinder, rectangular lamina). The combined translational and rotational motion of a rigid body on

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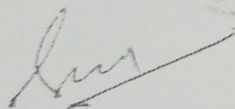
horizontal and inclined planes. Elasticity, relations between elastic constants, bending of beam and torsion of cylinder.

Unit V – Motion of Planets & Satellites

- Two particle central force problem, reduced mass, relative and centre of mass motion. Newton's law of gravitation, gravitational field and gravitational potential. Kepler's laws of planetary motion and their deductions. Motions of geo-synchronous & geo-stationary satellites and basic idea of Global Positioning System (GPS).

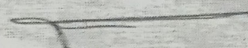
Suggested Readings:

1. Murray Spiegel, Seymour Lipschutz, Dennis Spellman, "Schaum's Outline Series: Vector Analysis", McGraw Hill, 2017, 2e
2. A.W. Joshi, "Matrices and Tensors in Physics", New Age International Private Limited, 1995, 3e
3. Charles Kittel, Walter D. Knight, Malvin A. Ruderman, Carl A. Helmholz, Burton J. Moyer, "Mechanics (In SI Units): Berkeley Physics Course Vol 1", McGraw Hill, 2017, 2e
4. Richard P. Feynman, Robert B. Leighton, Matthew Sands, "The Feynman Lectures on Physics - Vol. 1", Pearson Education Limited, 2012
5. Hugh D. Young and Roger A. Freedman, "Sears & Zemansky's University Physics with Modern Physics", Pearson Education Limited, 2017, 14e
6. D.S. Mathur, P.S. Hemne, "Mechanics", S. Chand Publishing, 1981, 3e



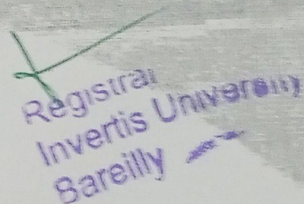
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