BEE404	Engineering Mechanics	3L:1T:0P	4 credits

Course Outcomes: At the end of this course, students will demonstrate the ability to
Understand the concepts of co-ordinate systems.
Analyse the three-dimensional motion.
Understand the concepts of rigid bodies.
Analyse the free-body diagrams of different arrangements.
Analyse torsional motion and bending moment.

Module 1: Introduction to vectors and tensors and co-ordinate systems (5 hours)
Introduction to vectors and tensors and coordinate systems; Vector and tensor algebra; Indical notation; Symmetric and anti-symmetric tensors; Eigenvalues and Principal axes.

Module 2: Three-dimensional Rotation (4 hours)
Three-dimensional rotation: Euler's theorem, Axis-angle formulation and Euler angles; Coordinate transformation of vectors and tensors.

Module 3: Kinematics of Rigid Body (6 hours)
Kinematics of rigid bodies: Dentition and motion of a rigid body; Rigid bodies as coordinate systems; Angular velocity of a rigid body, and its rate of change; Distinction between two- and three-dimensional rotational motion; Integration of angular velocity to find orientation; Motion relative to a rotating rigid body: Five term acceleration formula.

Module 4: Kinetics of Rigid Bodies (5 hours)
Kinetics of rigid bodies: Angular momentum about a point; Inertia tensor: Dentition and computation, Principal moments and axes of inertia, Parallel and perpendicular axes theorems; Mass moment of inertia of symmetrical bodies, cylinder, sphere, cone etc., Area moment of inertia and Polar moment of inertia, Forces and moments; Newton-Euler's laws of rigid body motion.

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Module 5: Free Body Diagram (1 hour)
Free body diagrams; Examples on modelling of typical supports and joints and discussion on the kinematic and kinetic constraints that they impose.

Module 6: General Motion (9 hours)
Examples and problems. General planar motions. General 3-D motions. Free precession, Gyroscopes, Rolling coin.

Module 7: Bending Moment (5 hours)
Transverse loading on beams, shear force and bending moment in beams, analysis of cantilevers, simply supported beams and overhanging beams, relationships between loading, shear force and bending moment, shear force and bending moment diagrams.

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Module 8: Torsional Motion (2 hours)

Torsion of circular shafts, derivation of torsion equation, stress and deformation in circular and hollow shafts.

Module 9: Friction (3 hours)

Concept of Friction; Laws of Coulomb friction; Angle of Repose; Coefficient of friction.

Text / References:

1. J. L. Meriam and L. G. Kraige, "Engineering Mechanics: Dynamics", Wiley, 2011.
2. M. F. Beatty, "Principles of Engineering Mechanics", Springer Science & Business Media, 1986.

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